# Bidirectional Full-Duplex MIMO Links at LargeSystem Limit 

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## Introduction

## General Topic: Full-Duplex Wireless

- "Full-duplex" wireless communication
= systems where some node(s) may transmit and receive simultaneously on a single frequency band
- Progressive physical/link-layer frequency-reuse concept
$=$ up to double spectral efficiency at system level, if the significant technical problem of self-interference is tackled
- Transmission and reception should use the band for the same amount of time to make the most of full duplex
$\triangleright$ (a)symmetry of traffic pattern, i.e., requested rates in the two simultaneous directions
$\triangleright$ (a)symmetry of channel quality, i.e.,
achieved rates in the two simultaneous directions


## Full-Duplex Communication Scenarios



1) Bidirectional communication link between two terminals

- Asymmetric traffic (typically)
- Symmetric channels (roughly)

2) Multihop relay link

- Symmetric traffic
- Asymmetric channels
- Direct link may be useful

3) Simultaneous down- and uplink for two half-duplex users

- Asymmetric traffic
- Asymmetric channels
- Inter-user interference!


## Scope: Rate Regions in Two-Way Communication



Transmission rate
from Terminal 1
to Terminal 2

- Bidirectional full-duplex multiantenna (MIMO) link
$\triangleright$ at the large-system limit
$\triangleright$ with asymmetric traffic
$\triangleright$ assuming symmetric setup for numerical results
- Achievable rate regions by controlling
$\triangleright$ spatial multiplexing
$\triangleright$ time sharing
- The analysis is based on the replica method borrowed from statistical physics


## Focus: Suppression vs. Cancellation without Tx

## Noise

Spatial-domain suppression:


Time-domain cancellation:


- The link needs efficient self-interference mitigation at both ends
$\triangleright$ Suppression: forming eigenbeams to transmit and receive in orthogonal directions ("null-space projection")
$\triangleright$ Cancellation: subtracting the interfering signal before decoder
- Both schemes can eliminate interference, but suppression is possible only at the cost of consuming spatial degrees of freedom


## System Model without Tx Noise

## Signal Model



- Terminal $i \in\{1,2\}$ has $M_{i}$ transmit and $N_{i}$ receive antennas
- In communication direction $i j \in\{12,21\}$ :

$$
\mathbf{y}_{j}=\mathbf{G}_{j} \mathbf{H}_{i j} \mathbf{F}_{i} \mathbf{x}_{i}+\mathbf{G}_{j} \mathbf{H}_{j j} \mathbf{F}_{j} \mathbf{x}_{j}+\mathbf{G}_{j} \mathbf{n}_{j}
$$

$\triangleright$ The link reserves $\hat{M}_{i}$ transmit and $\hat{N}_{j}$ receive streams for spatial multiplexing after self-interference mitigation

- Terminal $i$ does not know $\mathbf{H}_{i j}$ but Terminal $j$ knows $\mathbf{H}_{i j}$ and $\mathbf{H}_{j j}$


## Spatial-Domain Suppression



- Suppression exploits the transmit and receive beamforming filters:

$$
\mathbf{F}_{j} \in \mathbb{C}^{M_{j} \times \hat{M}_{j}} \quad \text { and } \quad \mathbf{G}_{j} \in \mathbb{C}^{\hat{N}_{j} \times N_{j}}
$$

$\triangleright$ Orthonormal spatial streams: $\mathbf{F}_{j}^{H} \mathbf{F}_{j}=\mathbf{I}$ and $\mathbf{G}_{j} \mathbf{G}_{j}^{H}=\mathbf{I}$

- Maximum for full-rank $\mathbf{H}_{j j}$ is $\hat{M}_{j}+\hat{N}_{j}=\max \left\{M_{j}, N_{j}\right\}$
- Self-interference is eliminated in Terminal $j$ if $\mathbf{G}_{j} \mathbf{H}_{j j} \mathbf{F}_{j}=\mathbf{0}$
$\triangleright$ Implemented using the SVD of $\mathbf{H}_{j j}$ (for instance)


## Time-Domain Cancellation



- Cancellation is based on the subtraction of the interfering signal so that decoder input becomes $\mathbf{y}_{j}-\mathbf{G}_{j} \mathbf{H}_{j j} \mathbf{F}_{j} \mathbf{x}_{j}$
$\triangleright$ Terminal $j \in\{1,2\}$ needs to know its own transmitted signal $\mathbf{x}_{j}$ which is not required with spatial-domain suppression
- All spatial degrees of freedom can be reserved for multiplexing
$\triangleright \hat{M}_{j}=M_{j}, \hat{N}_{j}=N_{j}$ and $\mathbf{F}_{j}=\mathbf{I}, \mathbf{G}_{j}=\mathbf{I}$ in the analysis


## Spatial-Division Multiplexing

Spatial-domain suppression:


Time-domain cancellation:


- After mitigation, the signal model is transformed to

$$
\mathbf{y}_{j}=\mathbf{G}_{j} \mathbf{H}_{i j} \mathbf{F}_{i} \mathbf{x}_{i}+\mathbf{G}_{j} \mathbf{n}_{j}, \quad \mathcal{E}\left\{\mathbf{x}_{i} \mathbf{x}_{i}^{H}\right\}=\left(1 / \hat{M}_{i}\right) \mathbf{I}
$$

$\triangleright$ Transmitter side: standard open-loop spatial multiplexing of independent Gaussian streams into $\mathrm{x}_{i}$
$\triangleright$ Receiver side: joint decoding for $\mathbf{y}_{j}$ knowing $\mathbf{G}_{j} \mathbf{H}_{i j} \mathbf{F}_{i} \in \mathbb{C}^{\hat{N}_{j} \times \hat{M}_{i}}$

- Time sharing between different stream configurations in order to make the achievable rate region convex with suppression


## Analytical Results

## Mutual Information

- We are interested in evaluating the average transmission rate as

$$
R_{i j}=\mathcal{E}\left\{\log \operatorname{det}\left(\mathbf{I}+\frac{1}{\hat{M}_{i}} \mathbf{G}_{j} \mathbf{H}_{i j} \mathbf{F}_{i}\left(\mathbf{G}_{j} \mathbf{H}_{i j} \mathbf{F}_{i}\right)^{H}\right)\right\}
$$

over the joint distribution of random matrices $\mathbf{G}_{j}, \mathbf{H}_{i j}$, and $\mathbf{F}_{i}$

- Instead, we begin from the definition of mutual information:

$$
\frac{R_{i j}}{\hat{M}_{i}}=\frac{\mathcal{E}\left\{\log p\left(\mathbf{y}_{j} \mid \mathbf{x}_{i}, \mathbf{G}_{j}, \mathbf{H}_{i j}, \mathbf{F}_{i}\right)\right\}}{\hat{M}_{i}}-\frac{\mathcal{E}\left\{\log \mathbf{E}_{\mathbf{x}_{i}}\left\{p\left(\mathbf{y}_{j} \mid \mathbf{x}_{i}, \mathbf{G}_{j}, \mathbf{H}_{i j}, \mathbf{F}_{i}\right)\right\}\right\}}{\hat{M}_{i}}
$$

where $p(\cdot \mid \cdot)$ is the Gaussian posterior probability

- The above expression can be transformed to

$$
\frac{R_{i j}}{\hat{M}_{i}}=-\frac{\hat{N}_{j}}{\hat{M}_{i}}-\frac{1}{\hat{M}_{i}} \lim _{u \rightarrow 0} \frac{\partial}{\partial u} \log \mathcal{E}\left\{\mathrm{E}_{\mathbf{x}_{i}}\left\{\exp \left(-\left\|\mathbf{y}_{j}-\mathbf{G}_{j} \mathbf{H}_{i j} \mathbf{F}_{i} \mathbf{x}_{i}\right\|^{2}\right)\right\}^{u}\right\}
$$

where the first term is trivial and the second term comes from the identity $\lim _{u \rightarrow 0} \frac{\partial}{\partial u} \log \mathcal{E}\left\{Z^{u}\right\}=\mathcal{E}\{\log Z\}$

## Replica Method and Integration

- With $\Delta \mathrm{x}_{a}=\mathrm{x}_{0}-\mathrm{x}_{a}$, the replica trick amounts to evaluating

$$
\frac{R_{i j}}{\hat{M}_{i}}=-\frac{\hat{N}_{j}}{\hat{M}_{i}}-\lim _{\hat{M}_{i} \rightarrow \infty} \frac{1}{\hat{M}_{i}} \lim _{u \rightarrow 0} \frac{\partial}{\partial u} \log \mathcal{E}\left\{\prod_{a=1}^{u} \mathrm{e}^{-\left\|\hat{M}_{i}^{-1 / 2} \mathbf{G}_{j} \mathbf{H}_{i j} \mathbf{F}_{i} \Delta \mathbf{x}_{a}+\mathbf{G}_{j} \mathbf{n}_{j}\right\|^{2}}\right\}
$$

where $u$ is an integer inside log but a real number outside $\log$ (!?)

- After Gaussian integration over $\mathbf{n}_{j}$ and $\mathbf{v}_{a}=\hat{M}_{i}^{-1 / 2} \mathbf{H}_{i j} \mathbf{F}_{i} \Delta \mathbf{x}_{a}$,

$$
\frac{R_{i j}}{\hat{M}_{i}}=-\frac{\hat{N}_{j}}{\hat{M}_{i}}-\lim _{\hat{M}_{i} \rightarrow \infty} \frac{1}{\hat{M}_{i}} \lim _{u \rightarrow 0} \frac{\partial}{\partial u} \log \mathcal{E}\left\{\mathrm{e}^{G\left(\mathbf{Q}, \mathbf{D}_{j}\right)}\right\}
$$

where $\{\mathbf{Q}\}_{a, b}=\frac{1}{M_{i}} \mathbf{x}_{b}^{H} \mathbf{x}_{a}$ and $\mathbf{D}_{j}=\mathbf{T}_{j}^{T} \mathbf{T}_{j}$ is binary and diagonal

- If the limits can be swapped, the saddle-point method implies

$$
\begin{aligned}
& \quad \frac{R_{i j}}{\hat{M}_{i}}=-\frac{\hat{N}_{j}}{\hat{M}_{i}}-\lim _{u \rightarrow 0} \frac{\partial}{\partial u} \lim _{\hat{M}_{i} \rightarrow \infty} \frac{1}{\hat{M}_{i}} \log \mathbf{E}_{\mathbf{D}_{j}}\left\{\exp \left(\hat{M}_{i} \underset{\mathbf{Q}, \tilde{\mathbf{Q}}}{\operatorname{extr}} T\left(\mathbf{Q}, \tilde{\mathbf{Q}}, \mathbf{D}_{j}\right)\right)\right\} \\
& \text { where } T\left(\mathbf{Q}, \tilde{\mathbf{Q}}, \mathbf{D}_{j}\right)=\frac{1}{\hat{M}_{i}} G\left(\mathbf{Q}, \mathbf{D}_{j}\right)-\operatorname{tr}(\mathbf{Q} \tilde{\mathbf{Q}})+\log M(\tilde{\mathbf{Q}})
\end{aligned}
$$

## Replica Symmetry Assumption and Extremization

- Before extremization, $T\left(\mathbf{Q}, \tilde{\mathbf{Q}}, \mathbf{D}_{j}\right)$ is transformed by replica symmetry

$$
\left(\mathbf{Q}=\mathbf{I}_{u+1}(p-q)+\mathbf{1}_{(u+1) \times(u+1)} q \quad \text { and } \quad \tilde{\mathbf{Q}}=\mathbf{I}_{u+1}(\tilde{p}-\tilde{q})+\mathbf{1}_{(u+1) \times(u+1)} \tilde{q}\right)
$$

to $T_{u}(p, q, \tilde{p}, \tilde{q})=-u \frac{\hat{N}_{j}}{M_{i}} \log \left(1+\bar{\gamma}_{i j}(p-q)\right)-(u+1)(p \tilde{p}+u q \tilde{q})+\log M(\tilde{\mathbf{Q}})$

- Matrix $\mathbf{D}_{j}$ also disappears and we get a tractable form as

$$
\frac{R_{i j}}{\hat{M}_{i}}=-\lim _{u \rightarrow 0} \frac{\partial}{\partial u} \operatorname{extrt}_{p, q, \tilde{p}, \tilde{q}} T_{u}(p, q, \tilde{p}, \tilde{q})
$$

which matches to the case of an i.i.d. Gaussian $\hat{M}_{i} \times \hat{N}_{j}$ channel

- Finally, we may exploit existing proofs (e.g., by Verdú) to obtain

$$
\frac{R_{i j}}{\hat{M}_{i}} \simeq \log \left(1+\frac{\hat{N}_{j}}{\hat{M}_{i}} \cdot \frac{\bar{\gamma}_{i j}}{1+E}\right)+\frac{\hat{N}_{j}}{\hat{M}_{i}}\left(\log (1+E)-\frac{E}{1+E}\right)
$$

where $E=\bar{\gamma}_{i j}(p-q)$ is a solution to $\frac{\bar{\gamma}_{i j}}{E}=1+\frac{\hat{N}_{j}}{\hat{M}_{i}} \cdot \frac{\bar{\gamma}_{i j}}{1+E}$
$\triangleright$ The achievable transmission rates of the two directions are indirectly coupled via $\hat{M}_{j}+\hat{N}_{j}=\max \left\{M_{j}, N_{j}\right\}$

## Numerical Results

## Example Setups

- The numerical results concentrate on symmetric systems where
$\triangleright M=M_{1}=M_{2}$
$\triangleright N=N_{1}=N_{2}$
$\triangleright \bar{\gamma}=\bar{\gamma}_{12}=\bar{\gamma}_{21}$
- However, some asymmetry should be taken into account
$\triangleright$ Requested rates may be different in the two directions, reflecting typical downlink/uplink imbalance ( $R_{12} / R_{21}$ )
$\triangleright$ There may be transmit/receive antenna imbalance ( $M / N$ )
- At the large-system limit, $M$ and $N$ grow asymptotically
- In summary, there are three key parameters to explore:
$R_{12} / R_{21} \quad \bar{\gamma} \quad M / N$


## Transmission Rate vs. SNR

- When

$$
\begin{aligned}
& \triangleright M=4 \\
& \triangleright N=8
\end{aligned}
$$

a) lines:
asymptotic analytical values projected to this finite case b) markers: accurate simulated values


- The asymptotic results are useful also for not-so-large systems
- Trade-off (indirect coupling) between rates in two directions: When choosing ( $\hat{M}_{i}, \hat{N}_{j}$ ) as a stream configuration in one direction, the opposite configuration becomes $\left(\hat{M}_{j}, \hat{N}_{i}\right)=\left(8-\hat{N}_{j}, 8-\hat{M}_{i}\right)$


## Achievable Rate Regions (1)

- When
$\triangleright M=4$
$\triangleright N=8$
$\triangleright \bar{\gamma}=8 \mathrm{~dB}$
- Varying $\hat{M}_{1}$ and $\hat{M}_{2}$ which sets
$\hat{N}_{1}=8-\hat{M}_{1}$
$\hat{N}_{2}=8-\hat{M}_{2}$
for suppression

- Each stream configuration $\left(\hat{M}_{1}, \hat{M}_{2}\right)$ renders a rectangular region
$\triangleright$ Suppression: 16 different two-way regions and two degenerate cases where data is transmitted in one direction only


## Achievable Rate Regions (2)

- When
$\triangleright M=4$
$\triangleright N=8$
$\triangleright \bar{\gamma}=8 \mathrm{~dB}$
- Varying $\hat{M}_{1}$ and $\hat{M}_{2}$ which sets
$\hat{N}_{1}=8-\hat{M}_{1}$
$\hat{N}_{2}=8-\hat{M}_{2}$
for suppression

- The complete rate region is achieved by time sharing between different fixed stream configurations ( $\hat{M}_{1}, \hat{M}_{2}$ )
$\triangleright$ The convex hull of the union of rectangular rate regions


## Achievable Rate Regions (3)

- When
$\triangleright M=4$
$\triangleright N=8$
$\triangleright \bar{\gamma}=8 \mathrm{~dB}$
- Varying continuously $\hat{M}_{1} / M$ and $\hat{M}_{2} / M$
- Using time sharing when $R_{12} \sim R_{21}$

- Rate region projected from the asymptotic analytical results (dashed line) matches well with the finite-case simulations


## Achievable Rate Regions vs. SNR

- When

$$
\begin{aligned}
& \triangleright(M, N)=(4,8) \\
& \qquad \bar{\gamma}=20 \mathrm{~dB} \\
& \quad=15 \mathrm{~dB} \\
& \quad=10 \mathrm{~dB} \\
& \quad=5 \mathrm{~dB} \\
& \quad=0 \mathrm{~dB} \\
& \quad=-5 \mathrm{~dB}
\end{aligned}
$$



- The absolute rates increase with the SNR value, as expected, but otherwise it affects only slightly the shape of rate regions
- Asymmetric traffic can be supported without time sharing


## Achievable Rate Regions vs. Antenna Imbalance

- When

$$
\begin{aligned}
& \triangleright(M, N)=(8,8) \\
&=(4,8) \\
&=(8,4) \\
&=(4,4) \\
& \triangleright \bar{\gamma}=12 \mathrm{~dB}
\end{aligned}
$$



- Transmit/receive antenna imbalance ( $M / N$ ) affects significantly the shape of the rate regions with spatial-domain suppression
- The rate region of suppression is always inside that of cancellation


## Suppression vs. Cancellation (SNR)



- SNR defines whether the performance is limited by transmit-side multiplexing gain or receive-side array gain
- Worst case: equal number of transmit and receive antennas


## Suppression vs. Cancellation (Antenna Imbalance)



- Transmit/receive antenna imbalance is a critical factor when characterizing the rate loss of suppression versus cancellation
- Having more transmit antennas than receive antennas is preferred


## Transmitter Noise and M(ism)atched Decoding

## Transmitter Noise and M(ism)atched Decoding



- Unknown transmit-side noise due to analog imperfections
$\triangleright$ nonlinear distortion, e.g., power amplifier (PA)
$\triangleright$ measured with EVM
- Feedback transmit-side noise may be on a par with the far-end signal due to the high gain of the near-end interference channel
$\triangleright$ Feedforward transmit-side noise can be neglected since it is typically below receive-side noise after channel attenuation
- Mitigation transparently around the actual multiplexing protocol which can operate without being aware of self-interference
$\triangleright$ Mismatched detection and decoding due to unexpected noise


## Focus: Self-interference Mitigation with Tx Noise

Spatial-domain suppression:


Time-domain cancellation:


- The link needs efficient self-interference mitigation at both ends
$\triangleright$ Suppression: receiving only in the null space of interference
$\triangleright$ Cancellation: subtracting the interfering signal before decoder
- Both can eliminate the data-dependent part of self-interference
- Suppression eliminates also the self-induced transmit-side noise, at the cost of consuming some spatial degrees of freedom


## System Model with Tx Noise

## Signal Model



- Terminal $i \in\{1,2\}$ has $M_{i}$ transmit and $N_{i}$ receive antennas
- In communication direction $i j \in\{12,21\}$ :

$$
\mathbf{y}_{j}=\mathbf{G}_{j} \mathbf{H}_{i j}\left(\mathbf{x}_{i}+\boldsymbol{m}_{i}\right)+\mathbf{G}_{j} \mathbf{H}_{j j}\left(\mathbf{x}_{j}+\boldsymbol{m}_{j}\right)+\mathbf{G}_{j} \mathbf{n}_{j}
$$

$\triangleright$ noise terms $\boldsymbol{m}_{i}$ and $\boldsymbol{m}_{j}$ due to transmitter imperfections
$\triangleright \hat{N}_{j}$ receive streams remain after self-interference mitigation

- Terminal $i$ does not know $\mathbf{H}_{i j}$ but Terminal $j$ knows $\mathbf{H}_{i j}$ and $\mathbf{H}_{j j}$


## Spatial-Domain Suppression



- In Terminal $j \in\{1,2\}$ after suppression using $\mathbf{G}_{j}$ of rank $\hat{N}_{j}$ :

$$
\mathbf{y}_{j}=\mathbf{G}_{j}(\mathbf{H}_{i j} \mathbf{x}_{i}+\underbrace{\mathbf{H}_{i j} \boldsymbol{m}_{i}}_{\approx \mathbf{0}})+\underbrace{\mathbf{G}_{j} \mathbf{H}_{j j}\left(\mathbf{x}_{j}+\boldsymbol{m}_{j}\right)}_{\text {eliminated when } \mathbf{G}_{j} \mathbf{H}_{j j}=\mathbf{0}}+\mathbf{G}_{j} \mathbf{n}_{j}
$$

- $\hat{N}_{j}=N_{j}-M_{j}$ if $\mathbf{H}_{j j}$ has full rank, thus requiring $N_{j}>M_{j}$
- When enclosing any conventional (e.g., half-duplex) transceiver by transparent suppression, it still performs matched decoding


## Time-Domain Cancellation



- In Terminal $j \in\{1,2\}$ after cancellation presuming $\mathbf{G}_{j}=\mathbf{I}$ :

$$
\mathbf{y}_{j}=\mathbf{H}_{i j} \mathbf{x}_{i}+\underbrace{\mathbf{H}_{i j} \boldsymbol{m}_{i}}_{\approx \mathbf{0}}+\underbrace{\mathbf{H}_{j j} \mathbf{x}_{j}}_{\text {eliminated }}+\mathbf{H}_{j j} \underbrace{\boldsymbol{m}_{j}}_{\text {unknown! }}+\mathbf{n}_{j}
$$

- $\hat{N}_{j}=N_{j}$, i.e., all degrees of freedom are saved for data reception
- Conventional receivers may adapt imperfectly to the presence of unexpected transmitter noise, leading to mismatched decoding


## Analytical Results

## Problem Statement

- "Unified" signal model: $\mathbf{y}_{j} \simeq \mathbf{G}_{j} \mathbf{H}_{i j} \mathbf{x}_{i}+\boldsymbol{w}_{j}$ where $\boldsymbol{w}_{j}=\mathbf{G}_{j} \mathbf{H}_{j j} \boldsymbol{m}_{j}+\mathbf{G}_{j} \mathbf{n}_{j}$ with $\boldsymbol{R}_{\boldsymbol{w}_{j}}=\frac{\sigma_{j}^{2}}{M_{j}} \mathbf{G}_{j} \mathbf{H}_{j j} \mathbf{H}_{j j}^{H} \mathbf{G}_{j}^{H}+\mathbf{I}$

1. Matched decoding uses the true density $p\left(\mathbf{y}_{j} \mid \mathbf{x}_{i}, \mathcal{H}_{i j}\right)$
2. Mismatched decoding estimates $\boldsymbol{R}_{\boldsymbol{w}_{j}}$ as $\tilde{\boldsymbol{R}}_{\boldsymbol{w}_{j}}$ and uses a postulated density $q\left(\mathbf{y}_{j} \mid \mathbf{x}_{i}, \mathcal{H}_{i j}\right)$

- Generalized mutual information (GMI) is defined as

$$
I_{\mathrm{gmi}}\left(\mathbf{y}_{j} ; \mathbf{x}_{i}\right)=\sup _{s>0} I_{\mathrm{gmi}}^{(s)}\left(\mathbf{y}_{j} ; \mathbf{x}_{i}\right)=\sup _{s>0}\left(\mathrm{E} \ln q\left(\mathbf{y}_{j} \mid \mathbf{x}_{i}, \mathcal{H}_{i j}\right)^{s}-\mathrm{E} \ln q^{(s)}\left(\mathbf{y}_{j} \mid \mathcal{H}_{i j}\right)\right)
$$

where $q^{(s)}\left(\mathbf{y}_{j} \mid \mathcal{H}_{i j}\right)=\mathrm{E}_{\mathbf{x}_{i}} q\left(\mathbf{y}_{j} \mid \mathbf{x}_{i}, \mathcal{H}_{i j}\right)^{s}$

- The first term is easy to calculate, yielding

$$
I_{\mathrm{gmi}}^{(s)}\left(\mathbf{y}_{j} ; \mathbf{x}_{i}\right)=\left(c-s \mathrm{E} \operatorname{tr}\left(\tilde{\boldsymbol{R}}_{\boldsymbol{w}_{j}}^{-1} \boldsymbol{R}_{\boldsymbol{w}_{j}}\right)\right)-\mathrm{E} \ln q^{(s)}\left(\mathbf{y}_{j} \mid \mathcal{H}_{i j}\right)
$$

while the second term needs special tricks as follows

## Replica Analysis

- Instead of trying direct calculation, let us take a different route and start by reformulating the difficult term as

$$
\mathrm{E} \ln q^{(s)}\left(\mathbf{y}_{j} \mid \mathcal{H}_{i j}\right)=c+\lim _{u \rightarrow 0} \frac{\partial}{\partial u} \ln \mathrm{E} Z\left(\mathbf{y}_{j}, \mathcal{H}_{i j} ; s\right)^{u}
$$

where $Z\left(\mathbf{y}_{j}, \mathcal{H}_{i j} ; s\right)=\mathrm{E}_{\mathbf{x}_{i}} \mathrm{e}^{-\left(\mathbf{y}_{j}-\mathbf{G}_{j} \mathbf{H}_{i j} \mathbf{x}_{i}\right)^{H} s \tilde{\boldsymbol{R}}_{\boldsymbol{w}_{j}}^{-1}\left(\mathbf{y}_{j}-\mathbf{G}_{j} \mathbf{H}_{i j} \mathbf{x}_{i}\right)}$

- To circumvent the problem of $u$ being real-valued, the replica trick then postulates

$$
Z\left(\mathbf{x}_{0}, \boldsymbol{w}_{j}, \mathcal{H}_{i j} ; s\right)^{u}=\mathrm{E}_{\left\{\mathbf{x}_{a}\right\}_{a=1}^{u}} \prod_{a=1}^{u} \mathrm{e}^{-\left[\boldsymbol{w}_{j}+\mathbf{G}_{j} \mathbf{H}_{i j}\left(\mathbf{x}_{0}-\mathbf{x}_{a}\right)\right]^{H} s \tilde{\boldsymbol{R}}_{w_{j}}^{-1}\left[\boldsymbol{w}_{j}+\mathbf{G}_{j} \mathbf{H}_{i j}\left(\mathbf{x}_{0}-\mathbf{x}_{a}\right)\right]}
$$

where $\mathbf{x}_{0}$ and $\left\{\mathbf{x}_{a}\right\}_{a=1}^{u}$ denote the original and replicated vectors

- If we manage to assess the above expectation as a function of $u$ when matrix dimensions in $\mathcal{H}_{i j}$ grow without bound with fixed ratios, analytically continuing $u \rightarrow 0$ recovers the per-stream GMI as

$$
\frac{1}{M} I_{\mathrm{gmi}}^{(s)}\left(\mathbf{y}_{j} ; \mathbf{x}_{i}\right)=-\frac{s}{M} \mathrm{E} \operatorname{tr}\left(\tilde{\boldsymbol{R}}_{\boldsymbol{w}_{j}}^{-1} \boldsymbol{R}_{\boldsymbol{w}_{j}}\right)-\lim _{M \rightarrow \infty} \frac{1}{M} \lim _{u \rightarrow 0} \frac{\partial}{\partial u} \ln \mathrm{E} Z\left(\mathbf{x}_{0}, \boldsymbol{w}_{j}, \mathcal{H}_{i j} ; s\right)^{u}
$$

## Matched Decoding: Per-stream Achievable Rate

- When $\mathbf{H}_{i j}$ and $\mathbf{H}_{j j}$ are i.i.d. Gaussian with gains $\bar{\gamma}_{i j}$ and $\bar{\gamma}_{j j}$ and the receiver adapts perfectly to residual self-interference:

$$
\frac{R_{i j}}{M_{i}}=\ln \left(1+\eta_{i j}\right)-\frac{\eta_{i j}}{1+\eta_{i j}}+\frac{1}{\alpha_{i j}}\left[I\left(\alpha_{j j}, \bar{\gamma}_{j j} \sigma_{j}^{2} ; 1+\frac{\bar{\gamma}_{i j}}{1+\eta_{i j}}\right)-I\left(\alpha_{j j}, \bar{\gamma}_{j j} \sigma_{j}^{2} ; 1\right)\right]
$$

for which the fixed-point $\eta_{i j}$ is found numerically by iterating

$$
\eta_{i j}=\frac{\bar{\gamma}_{i j}}{\alpha_{i j}}\left[\frac{1}{1+\frac{\bar{\gamma}_{i j}}{1+\eta_{i j}}}-\frac{\alpha_{i i}}{4 \bar{\gamma}_{j j} \sigma_{j}^{2}} \mathcal{F}\left(\frac{\bar{\gamma}_{j j} \sigma_{j}^{2}}{\alpha_{i i}} \cdot \frac{1}{1+\frac{\bar{\gamma}_{i j}}{1+\eta_{i j}}}, \alpha_{i i}\right)\right]
$$

and the auxiliary functions are given by

$$
\begin{gathered}
\mathcal{F}(x, \beta)=\left(\sqrt{x(1+\sqrt{\beta})^{2}+1}-\sqrt{x(1-\sqrt{\beta})^{2}+1}\right)^{2} \\
I\left(\beta, \sigma^{2} ; t\right)=\ln t+\beta \ln \left[1+\frac{\sigma^{2}}{t \beta}-\frac{1}{4} \mathcal{F}\left(\frac{\sigma^{2}}{t \beta}, \beta\right)\right]+\ln \left[1+\frac{\sigma^{2}}{t}-\frac{1}{4} \mathcal{F}\left(\frac{\sigma^{2}}{t \beta}, \beta\right)\right]-\frac{t \beta}{4 \sigma^{2}} \mathcal{F}\left(\frac{\sigma^{2}}{t \beta}, \beta\right)
\end{gathered}
$$

- N.B.: This result is for cancellation only


## Mismatched Decoding: Per-stream Achievable Rate

- When $\mathbf{H}_{i j}$ and $\mathbf{H}_{j j}$ are i.i.d. Gaussian with gains $\bar{\gamma}_{i j}$ and $\bar{\gamma}_{j j}$ and the receiver postulates imperfectly $\tilde{\boldsymbol{R}}_{\boldsymbol{w}_{j}}=\left(1+\bar{\gamma}_{j j} \tilde{\sigma}_{j}^{2}\right) \mathbf{I}_{N}$ :

$$
\frac{R_{i j}}{M_{i}}=-\frac{s\left(1+\bar{\gamma}_{j j} \sigma_{j}^{2}\right)}{\alpha_{i j}\left(1+\bar{\gamma}_{j j} \tilde{\sigma}_{j}^{2}+s \tilde{E}_{i j}\right)} \cdot \frac{s \tilde{E}_{i j}}{1+\bar{\gamma}_{j j} \tilde{\sigma}_{j}^{2}}+\ln \left(1+\frac{s \bar{\gamma}_{i j}}{\alpha_{i j}\left(1+\bar{\gamma}_{j j} \tilde{\sigma}_{j}^{2}+s \tilde{E}_{i j}\right)}\right)+\frac{1}{\alpha_{i j}} \ln \left(1+\frac{s \tilde{E}_{i j}}{1+\bar{\gamma}_{j j} \tilde{\sigma}_{j}^{2}}\right)
$$

where $\tilde{E}_{i j}$ is directly given as

$$
\tilde{E}_{i j}=\frac{s \bar{\gamma}_{i j}-\left(1+\bar{\gamma}_{j j} \tilde{\sigma}_{j}^{2}\right)}{2 s}-\frac{\bar{\gamma}_{i j}}{2 \alpha_{i j}}+\sqrt{\frac{\left(1+\bar{\gamma}_{j j} \tilde{\sigma}_{j}^{2}\right) \bar{\gamma}_{i j}}{s}+\left(\frac{s \bar{\gamma}_{i j}-\left(1+\bar{\gamma}_{j j} \tilde{\sigma}_{j}^{2}\right)}{2 s}-\frac{\bar{\gamma}_{i j}}{2 \alpha_{i j}}\right)^{2}}
$$

$\triangleright$ the case of $\tilde{\sigma}_{j}^{2}=0$ is illustrated in the numerical examples
$\triangleright$ asymptotic result at large-system limit: $M_{i} \rightarrow \infty$ and $N_{j} \rightarrow \infty$ while $\frac{M_{i}}{N_{j}} \rightarrow \alpha_{i j}$ for all $i, j \in\{1,2\}$ (like in the previous slide)

- Optimization is required for the parameter $s$ though, in order to find more tight lower bounds for the maximum achievable rate


## Numerical Examples

## Example Setups

- The numerical results concentrate on symmetric systems where
$\triangleright M=M_{1}=M_{2}$
$\triangleright N=N_{1}=N_{2}$
$\triangleright \bar{\gamma}=\bar{\gamma}_{12}=\bar{\gamma}_{21}$
$\triangleright \bar{\gamma}_{\mathrm{I}}=\bar{\gamma}_{11}=\bar{\gamma}_{22}$
$\triangleright \sigma^{2}=\sigma_{1}^{2}=\sigma_{2}^{2}$
- There may be transmit/receive antenna imbalance ( $M / N$ )
$\triangleright$ Yet $M$ and $N$ grow asymptotically at the large-system limit
- Choice $\sigma^{2}=0.001$ corresponds to transmitter EVM of -30 dB (or equivalently $3.2 \%$ ) which is a practical but slightly optimistic value
- In summary, there are three key parameters to explore:

| $\bar{\gamma}$ | $\bar{\gamma}_{I}$ | $M / N$ |
| :--- | :--- | :--- |

## Achievable Rates vs. SNR (Fig. 2)


(a) $M=4, N=8, \bar{\gamma}_{I}=33 \mathrm{~dB}$

(b) $M=4, N=6, \bar{\gamma}_{\mathrm{I}}=39 \mathrm{~dB}$

- Simulations (markers) corroborate analytical results (solid lines)
(a) when $M / N \leq 1 / 2$, suppression reduces receive array gain
(b) when $M / N>1 / 2$, suppression reduces multiplexing order


## Achievable Rates vs. SNR, Discrete Modulation


(a) $M=4, N=8, \bar{\gamma}_{\mathrm{I}}=33 \mathrm{~dB}$

(b) $M=4, N=6, \bar{\gamma}_{\mathrm{I}}=39 \mathrm{~dB}$

## Matched Decoding: Suppression vs. Cancellation [\%]


(a) $M / N=1 / 2$

(b) $M / N=2 / 3$

- Suppression is worse than cancellation if matched decoding is still feasible under residual self-interference, since such receivers already comprise ideal interference and noise control


## Mismatched Decoding: Suppression vs. Cancellation [\%]


(a) $M / N=1 / 2$

(b) $M / N=2 / 3$

- Transmitter noise and mismatched decoding cause an intricate interplay between the parameters corresponding to the channel gains of the data and self-interference links and the antenna ratio


## Mismatched Decoding: Switching Boundaries



- Suppression becomes preferred in wide SNR range when the number of receive antennas vs. transmit antennas is large
- The level of self-interference is a significant factor at low SNR


## Conclusion

## Conclusion

- Achievable rates in bidirectional full-duplex link
- Comparison of spatial suppression and subtractive cancellation
$\triangleright$ for characterizing the cost and benefit of allocating a part of spatial degrees of freedom for self-interference mitigation
$\triangleright$ Trade-off between reduced multiplexing order or array gain and residual self-interference
- Mismatched decoding due to transmitter imperfections
- Analysis at the large-system limit based on the replica method
$\triangleright$ Monte Carlo simulations with small number of antennas match well with the corresponding asymptotic results



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